FIG. 1(a)

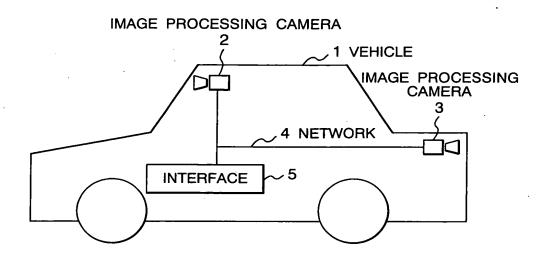
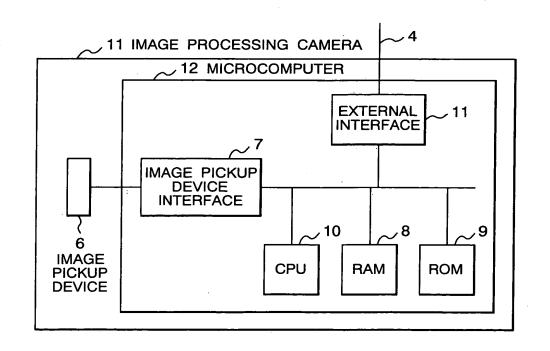


FIG. 1(b)



| APPLICATION                         | IMAGE<br>QUALITY | RATE   | CAMERA CONTROL                            | IMAGE PROCESSING FUNCTION                                       |
|-------------------------------------|------------------|--------|---|---|
| MONITORING                          | 1                | HSIH   | FOR MONITORING                            | IMAGE DOWNSCALING AND<br>EDGE ENHANCEMENT                       |
| DRIVE RECORDER                      | ı                | TOW    | FOR MONITORING                            | IMAGE COMPRESSION AND DATA INTEGRATION                          |
| VIDEO ALBUM<br>(HIGH IMAGE QUALITY) | HIGH             | нвн    | FOR MONITORING                            | IMAGE COMPRESSION AND COLOR CORRECTION                          |
| VIDEO ALBUM<br>(LOW IMAGE QUALITY)  | row              | гом    | FOR MONITORING                            | IMAGE COMPRESSION AND COLOR CORRECTION                          |
| AUTOMATIC LIGHT<br>CONTROL          | ı                | ПОМ    | FAST/SLOW SHUTTERING<br>AND COLOR CONTROL | MEASUREMENT OF EXTERNAL ILLU-<br>MINATION AND VEHICLE DETECTION |
| LANE DEVIATION ALARM                | I                | MEDIUM | FAST/SLOW SHUTTERING                      | LANE RECOGNITION  |
| INTRUDING VEHICLE<br>ALARM          | 1 ·              | MEDIUM | FAST/SLOW SHUTTERING<br>AND COLOR CONTROL | LANE RECOGNITION AND VEHICLE DETECTION                          |
| PASSING VEHICLE ALARM               | I                | MEDIUM | FAST/SLOW SHUTTERING<br>AND COLOR CONTROL | VEHICLE DETECTION   |
| PARKING ASSISTANCE                  | 1                | LOW    | FAST/SLOW SHUTTERING                      | OBSTACLE DETECTION AND PARKING-FRAME DETECTION                  |
| LANE KEEPING<br>ASSISTANCE          |                  | МЕБІОМ | FAST/SLOW SHUTTERING                      | LANE RECOGNITION  |
| COLLISION ALLEVIATION               | ı                | HIGH   | OPTIMUM SHUTTERING                        | DETECTION OF VEHICLES<br>AND OBSTACLES                          |
| COLLISION AVOIDANCE                 | I                | HIGH   | OPTIMUM SHUTTERING                        | LANE RECOGNITION AND DETECTION OF VEHICLES AND OBSTACLES        |

(-: NOT DEFINED)

FIG. 3

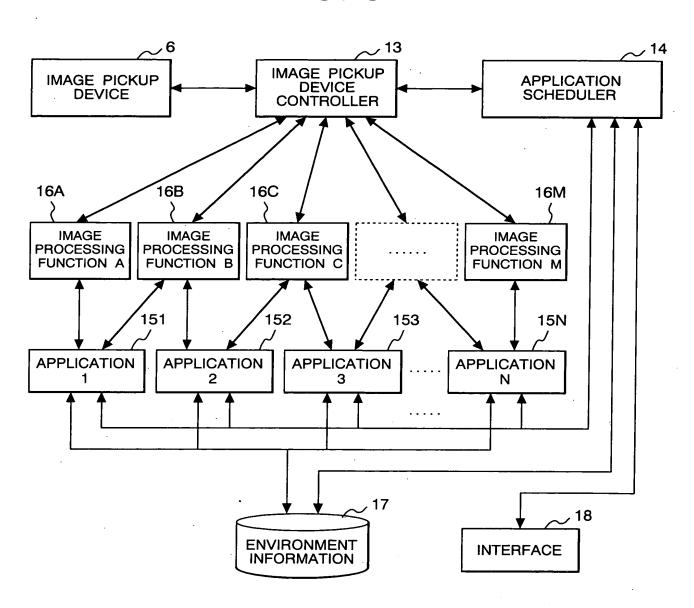


FIG. 4

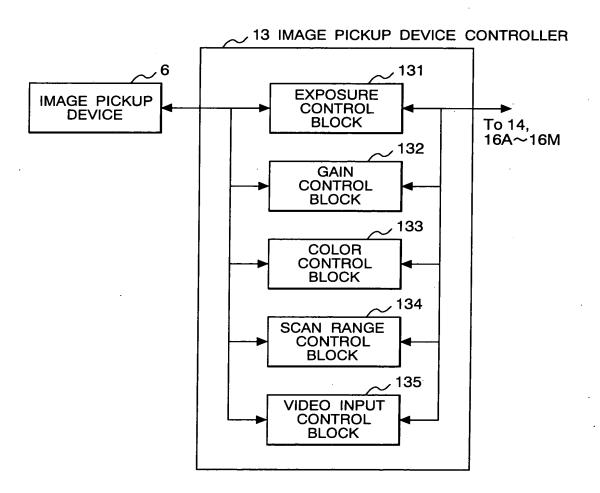


FIG. 5

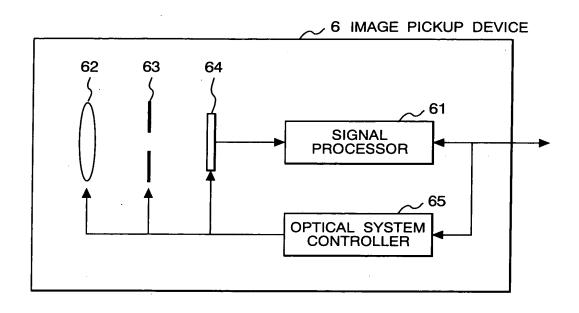


FIG. 6

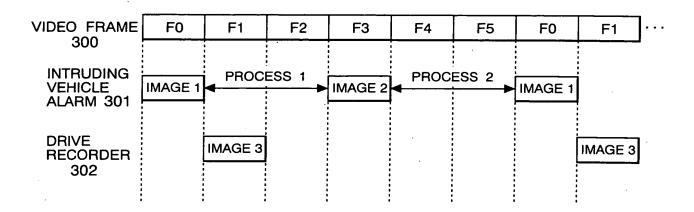


FIG. 7

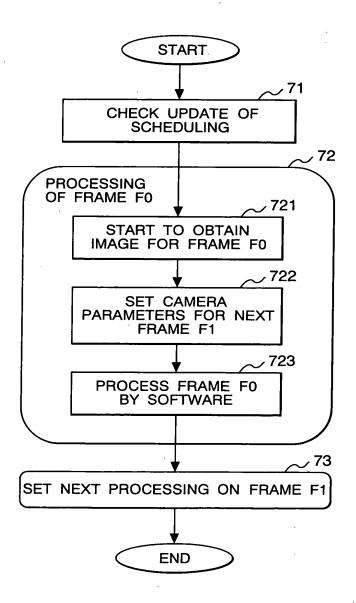


FIG. 8(a)

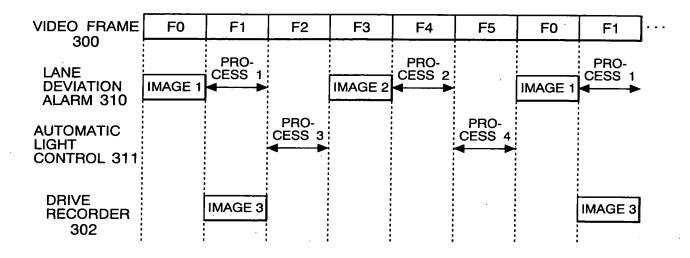


FIG. 8(b)

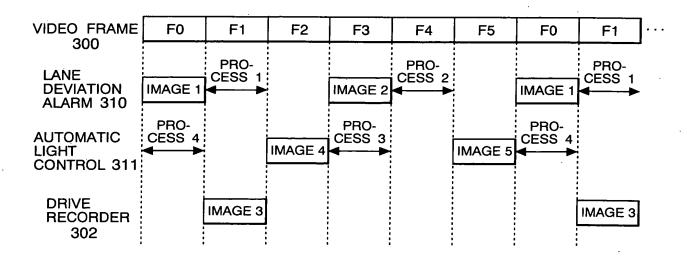


FIG. 9(a)

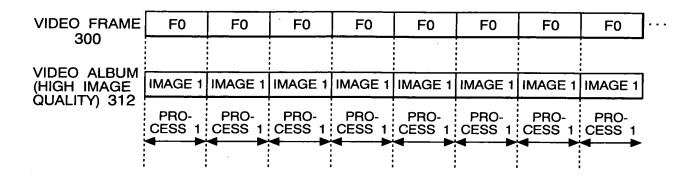


FIG. 9(b)

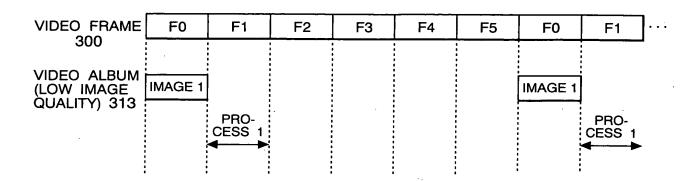


FIG. 10(a)

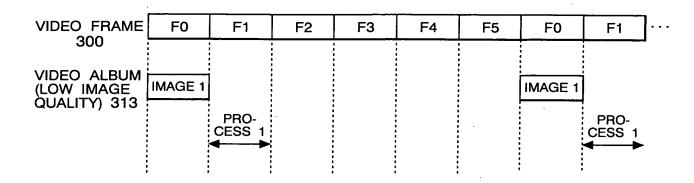
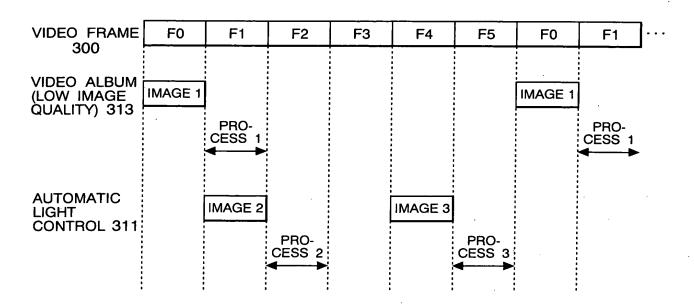
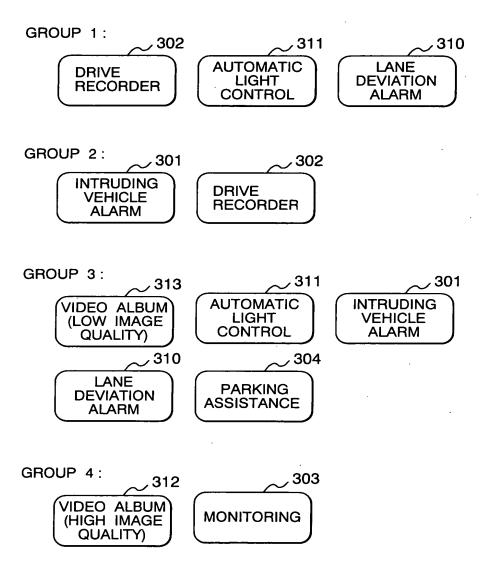
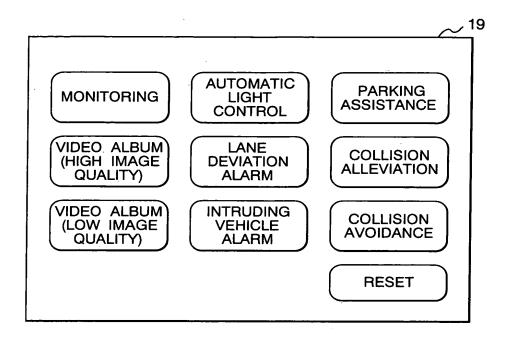
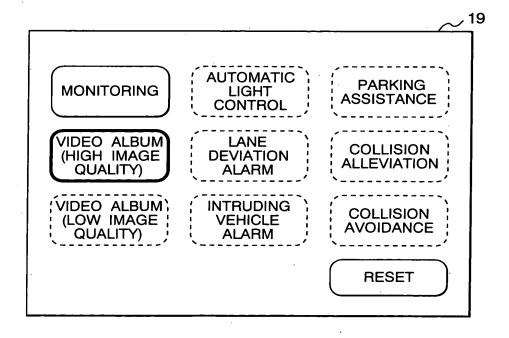


FIG. 10(b)









## FIG. 14(a)

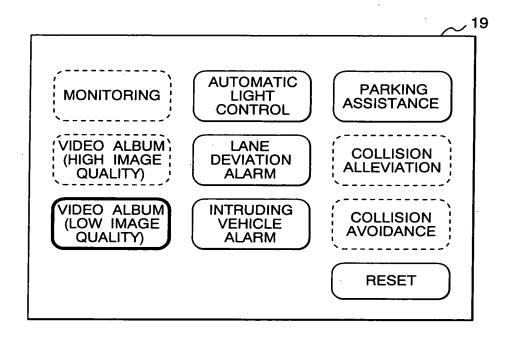


FIG. 14(b)

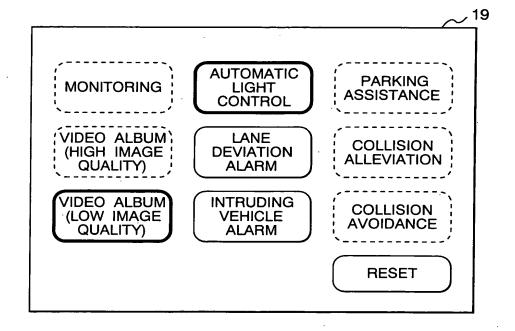
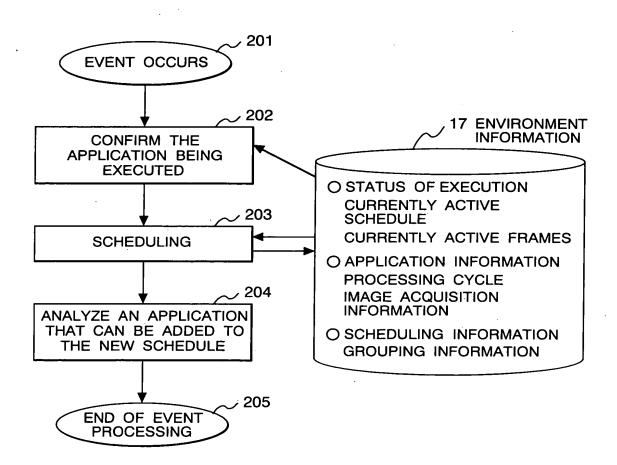


FIG. 15



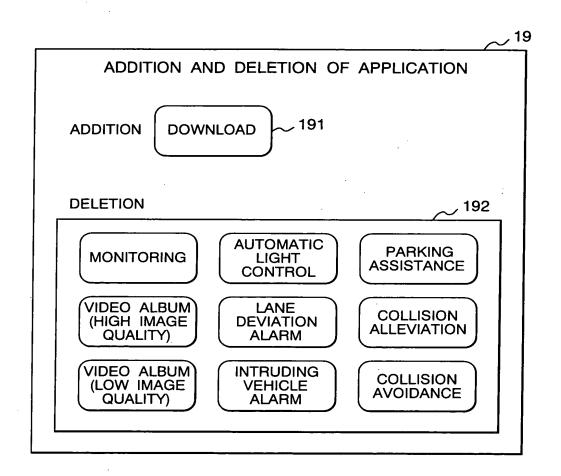


FIG. 17

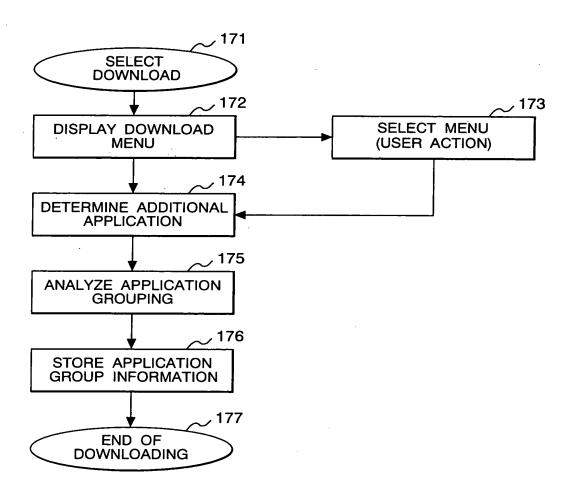


FIG. 18

